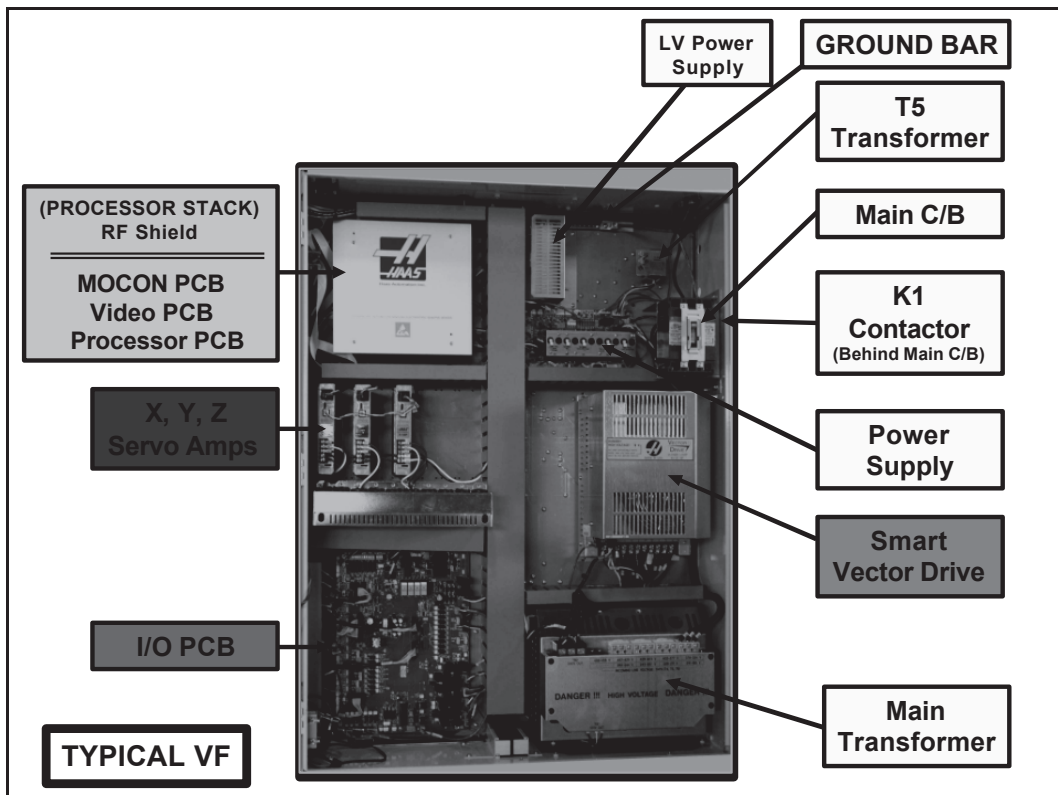


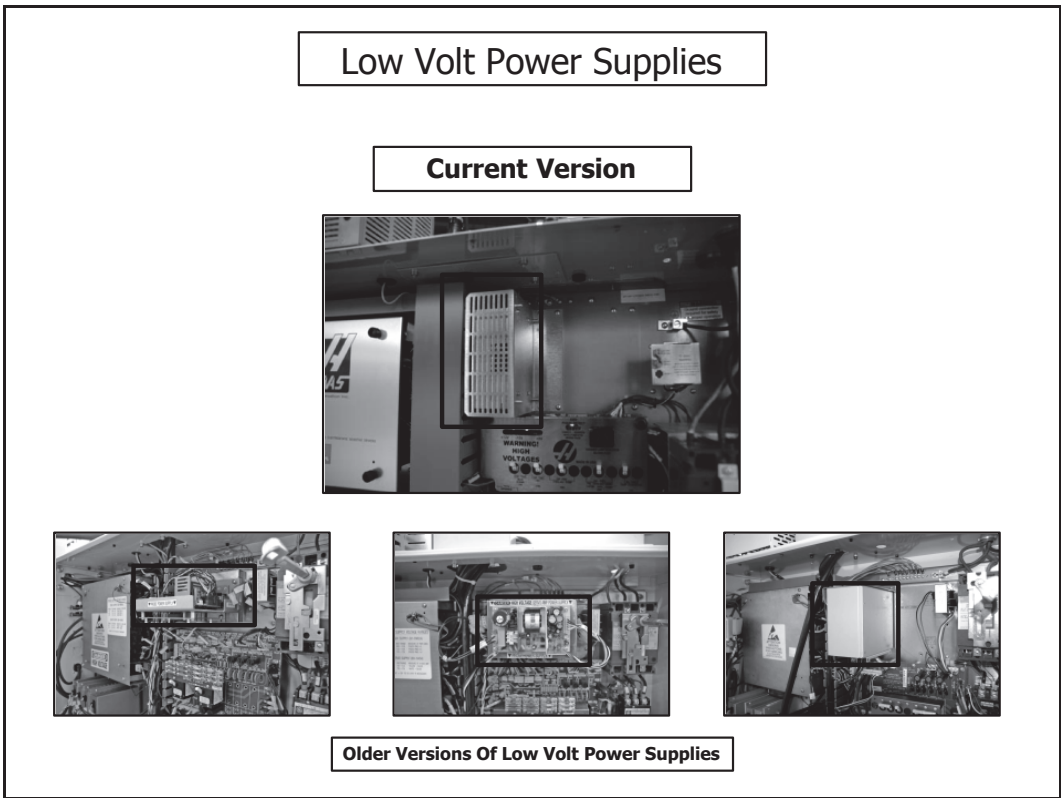
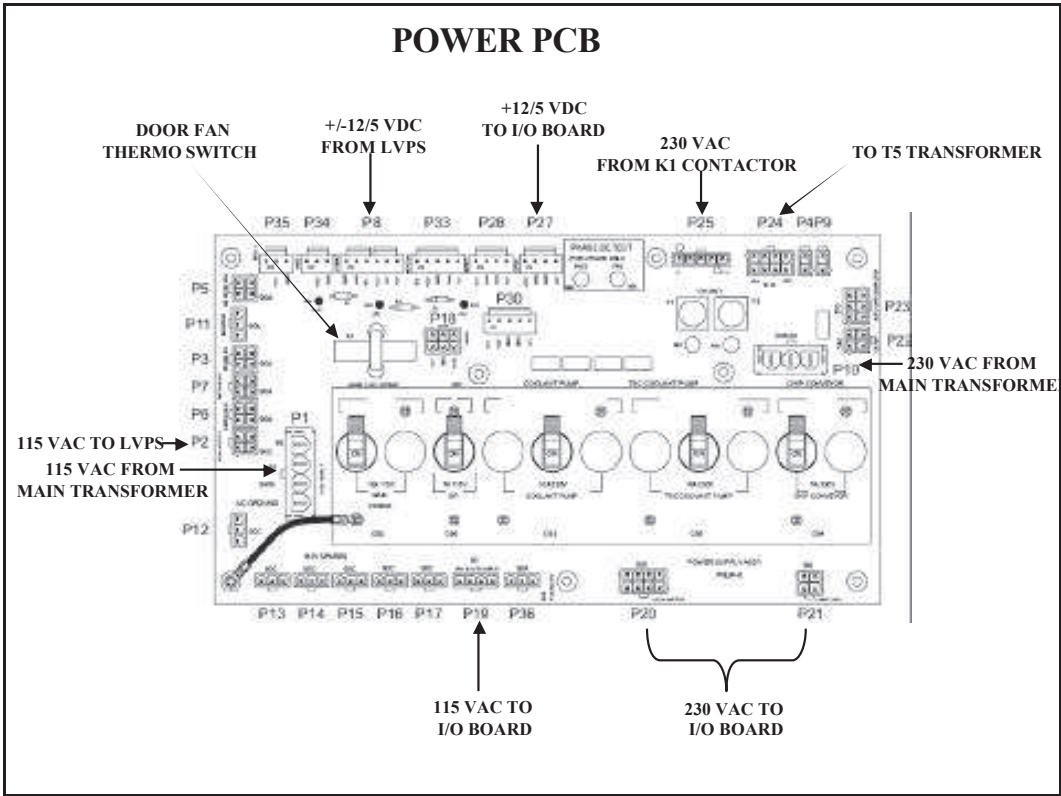
HAAS AUTOMATION TRAINING

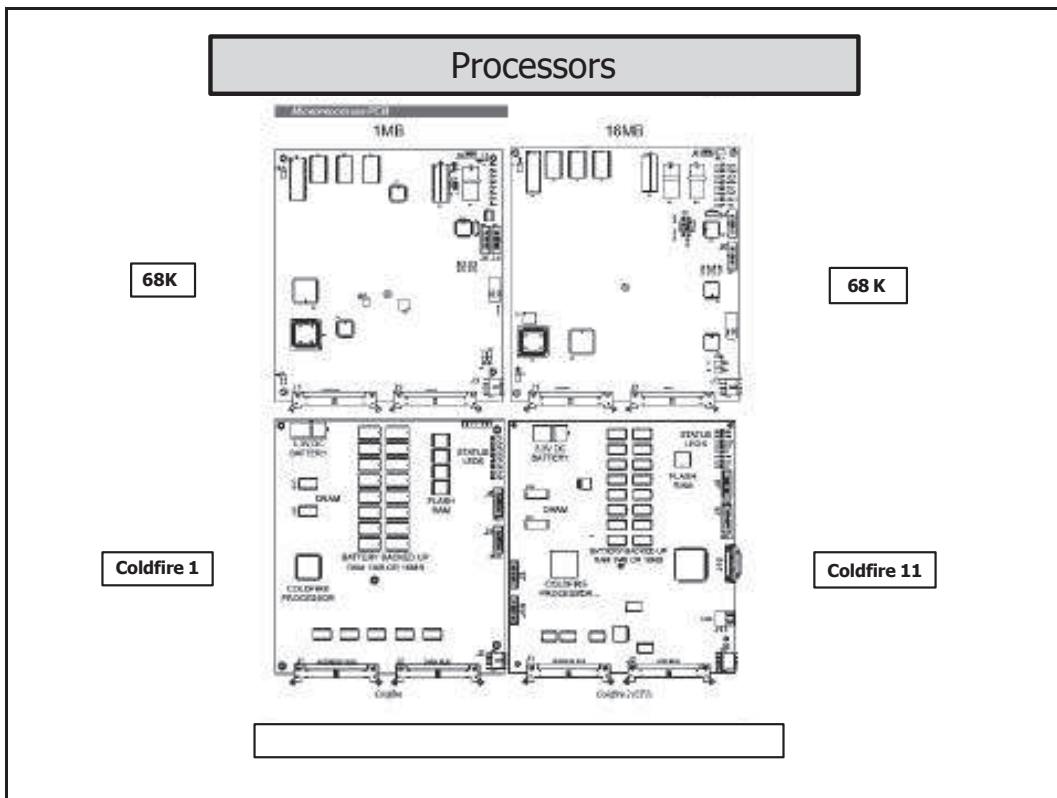
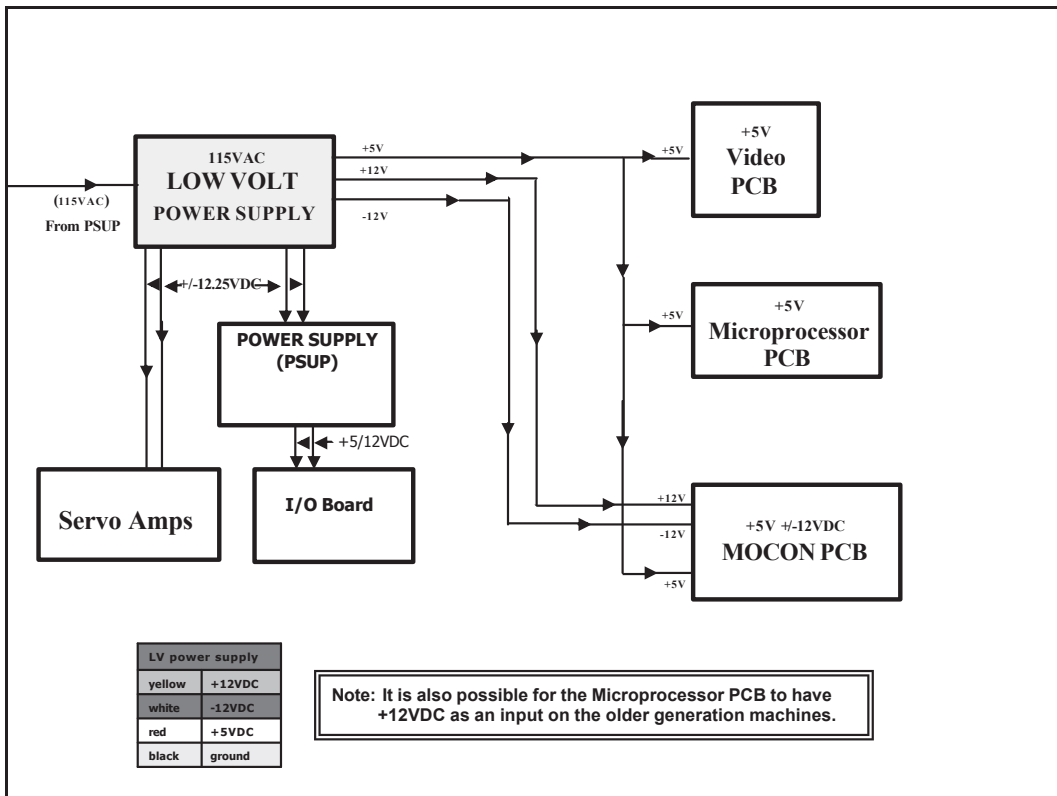


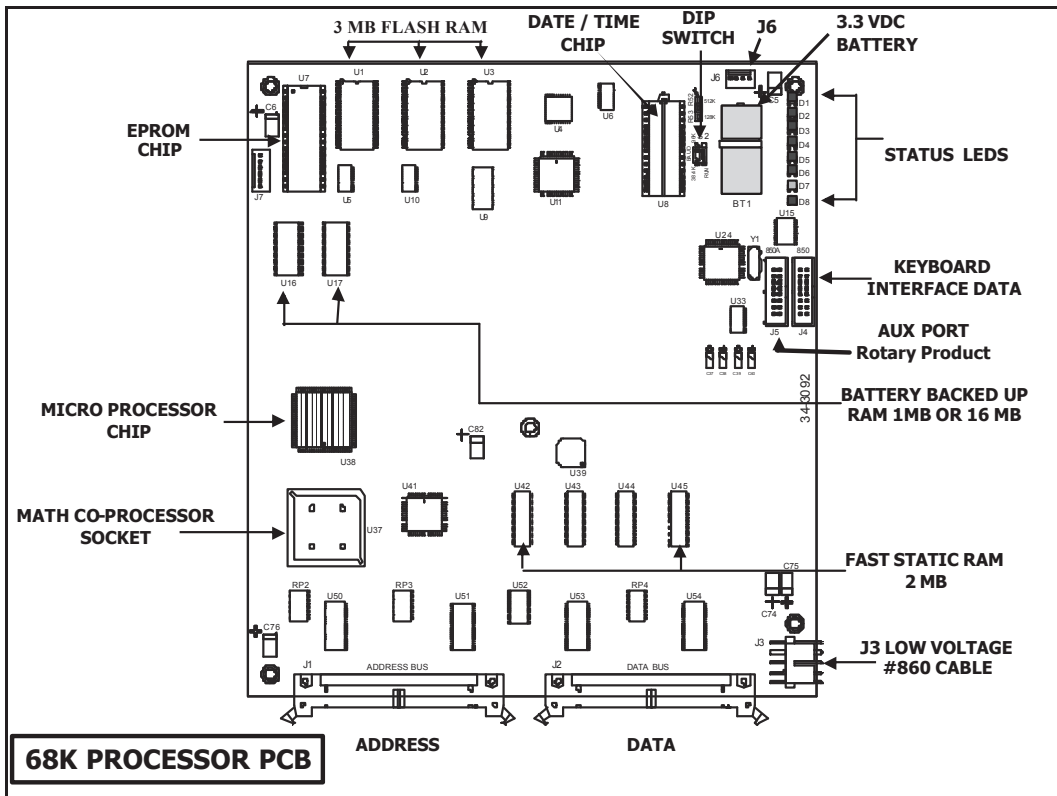
PRESENTS

**PRINTED CIRCUIT BOARDS
PCB's**



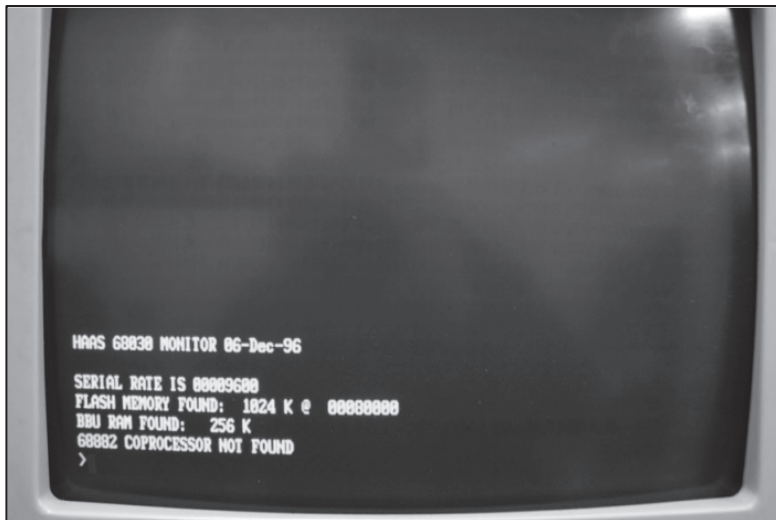


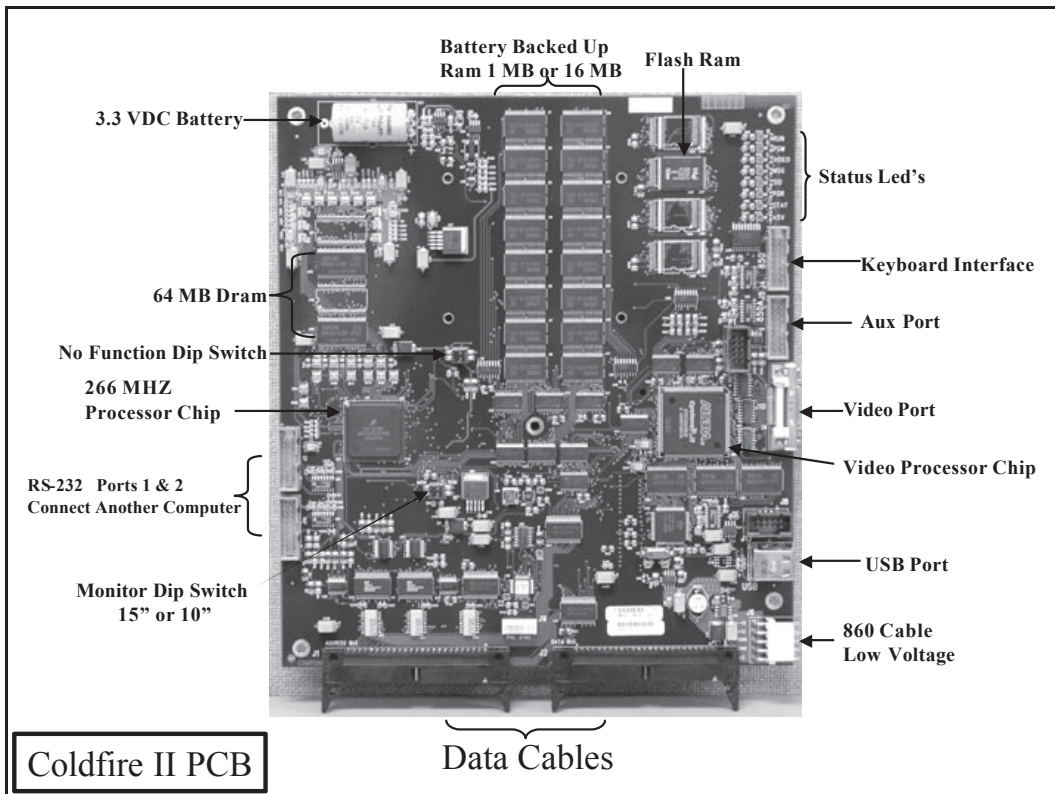




68K Processor

(13.xx and earlier software)

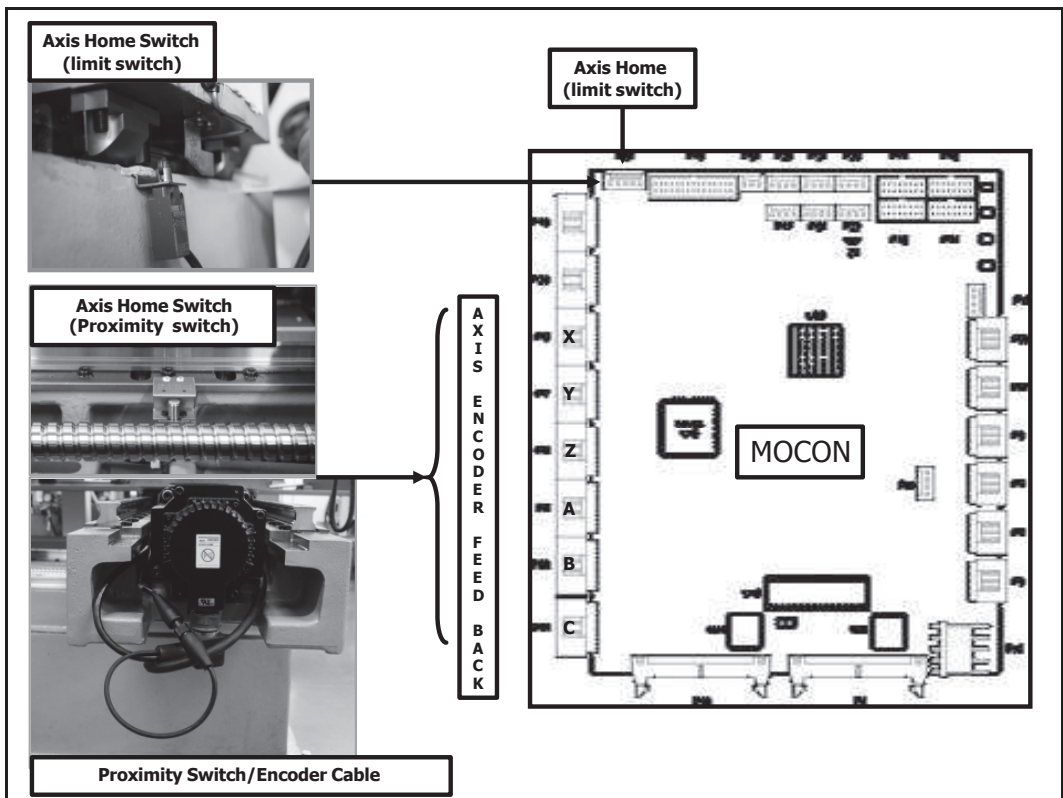
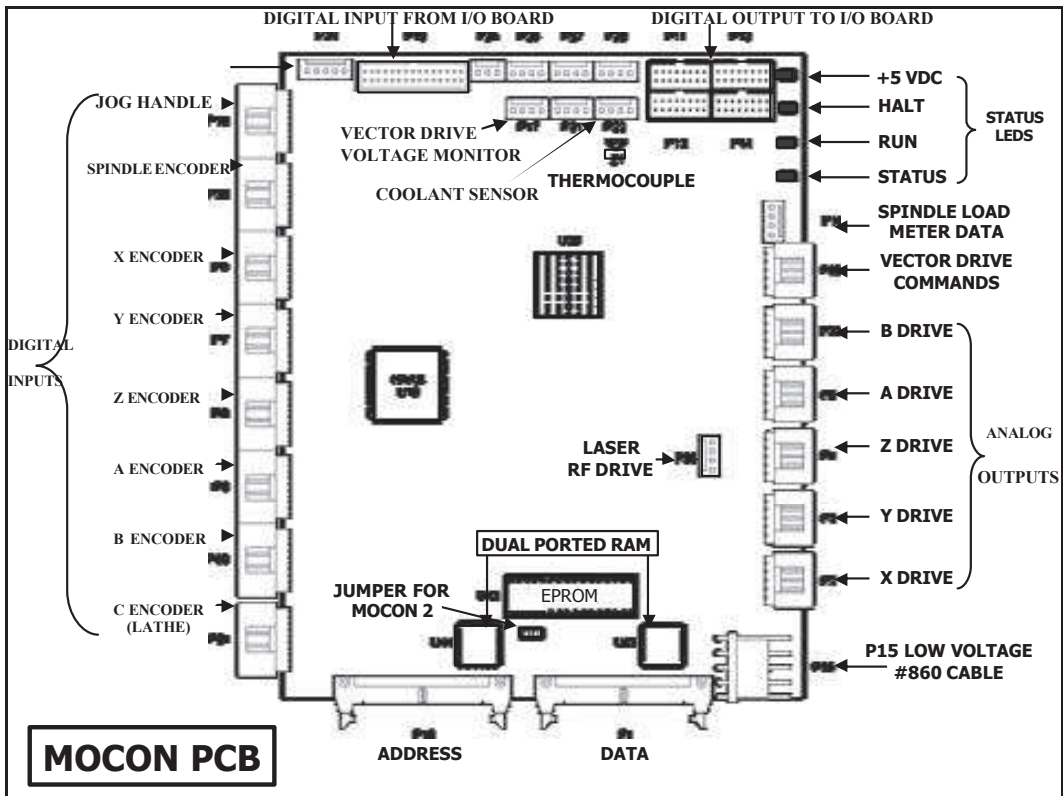




This shows how you can tell if there is a Coldfire Processor. This is the text that you will see when you press <PRGM/CONVRS> while turning on the control. You also need to check the Monitor Rev. Version 1.12R or LATER is required. The Software Readme file has instructions for updating the Monitor software.

→ Haas 266 Mhz Coldfire Monitor – Rev. 1.10 Dec 19 2005
Press H or ? for Help

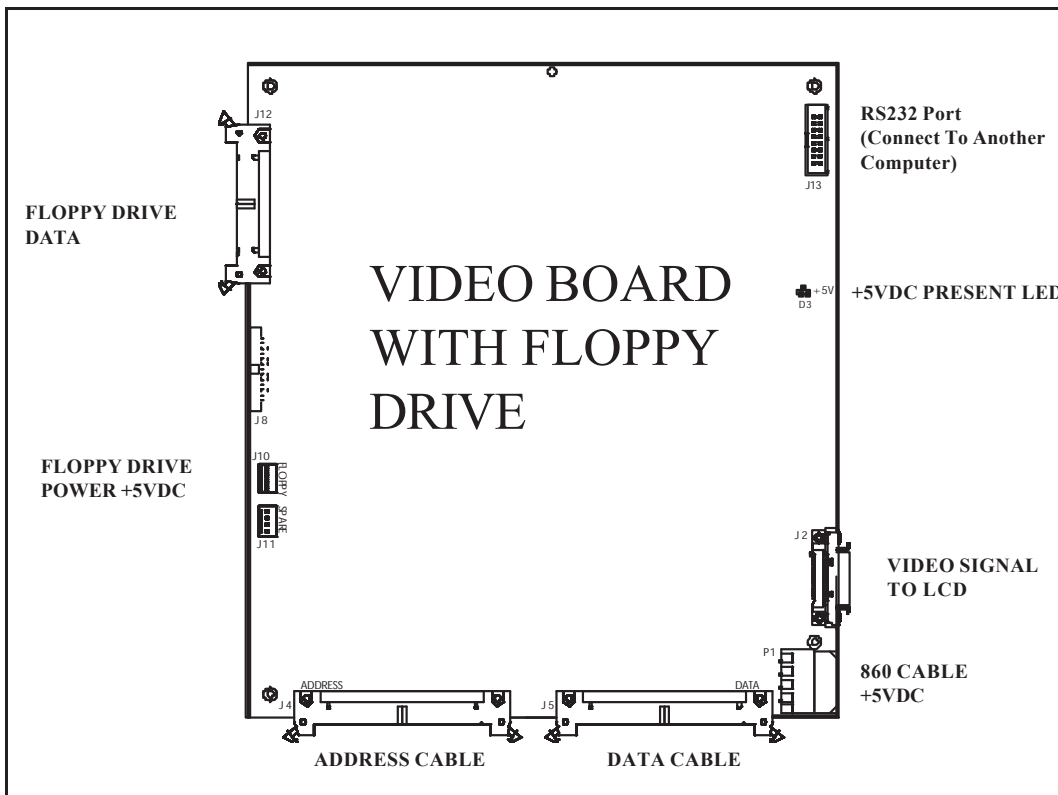
SERIAL RATE IS 00009600
CALCULATED MONITOR CRC IS: 0000EC26
FLASH MEMORY FOUND: 8 Mb
BBU RAM FOUND; 1 Mb
FPU FOUND
>_



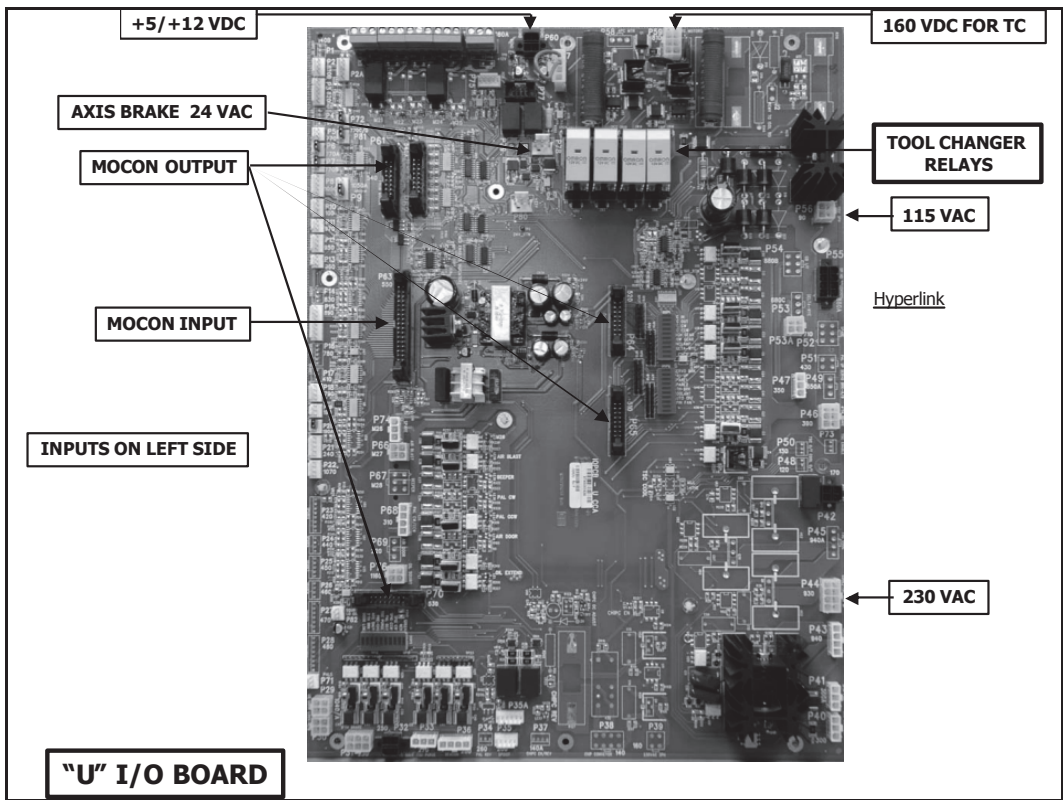
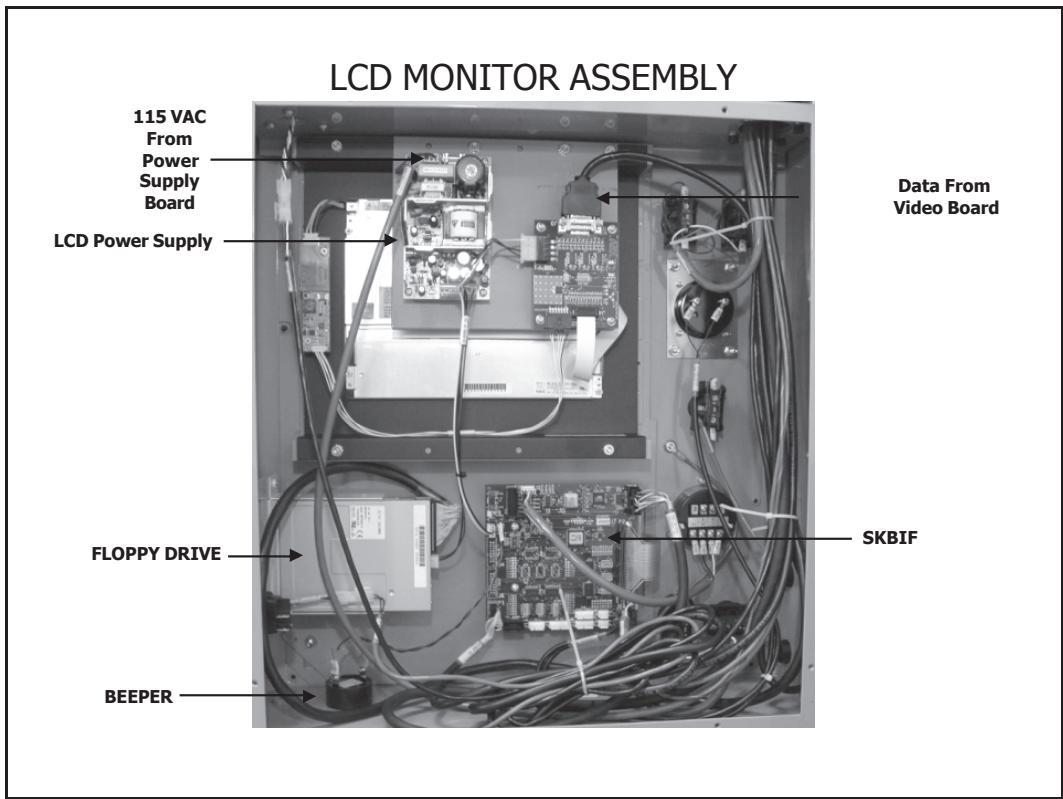
MOCON CAUSED ALARM

ALARM 157

MOCON WATCHDOG FAULT

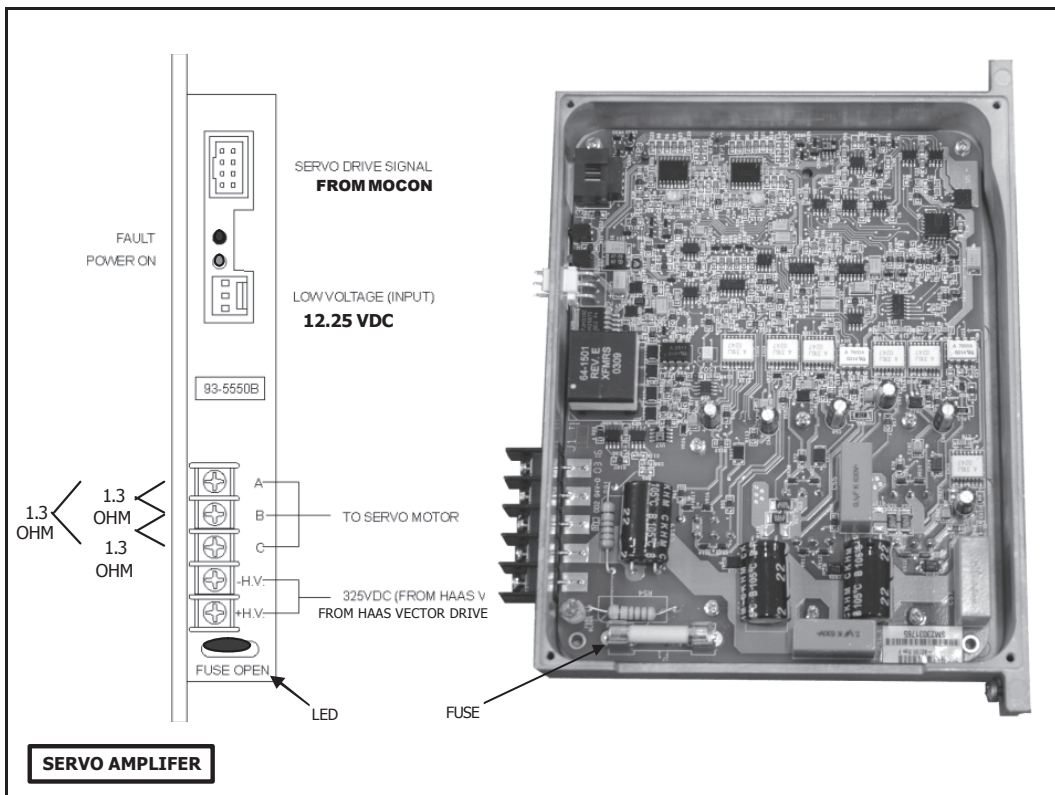


LCD MONITOR ASSEMBLY



I/O RELEASE NOTES

ALWAYS REFER TO THE RELEASE NOTES FOR THE I/O BOARD YOU ARE INSTALLING



IOPCB-U RELEASE NOTES

Rev. A – Production Release.

Rev. B – Added instructions for J1 & J2 (step5,8) Removed Pot. R119 and added instructions for the adjustment of R122 (step6)

Rev. C – Correct the DESCRIPTION to delete “This board also requires the PSUP-K or later”

DESCRIPTION

IOPCB-U is designed for new machines only. It is completely interchangeable and backward compatible with IO-S and IO-T only.

INTERCHANGE ABILITY

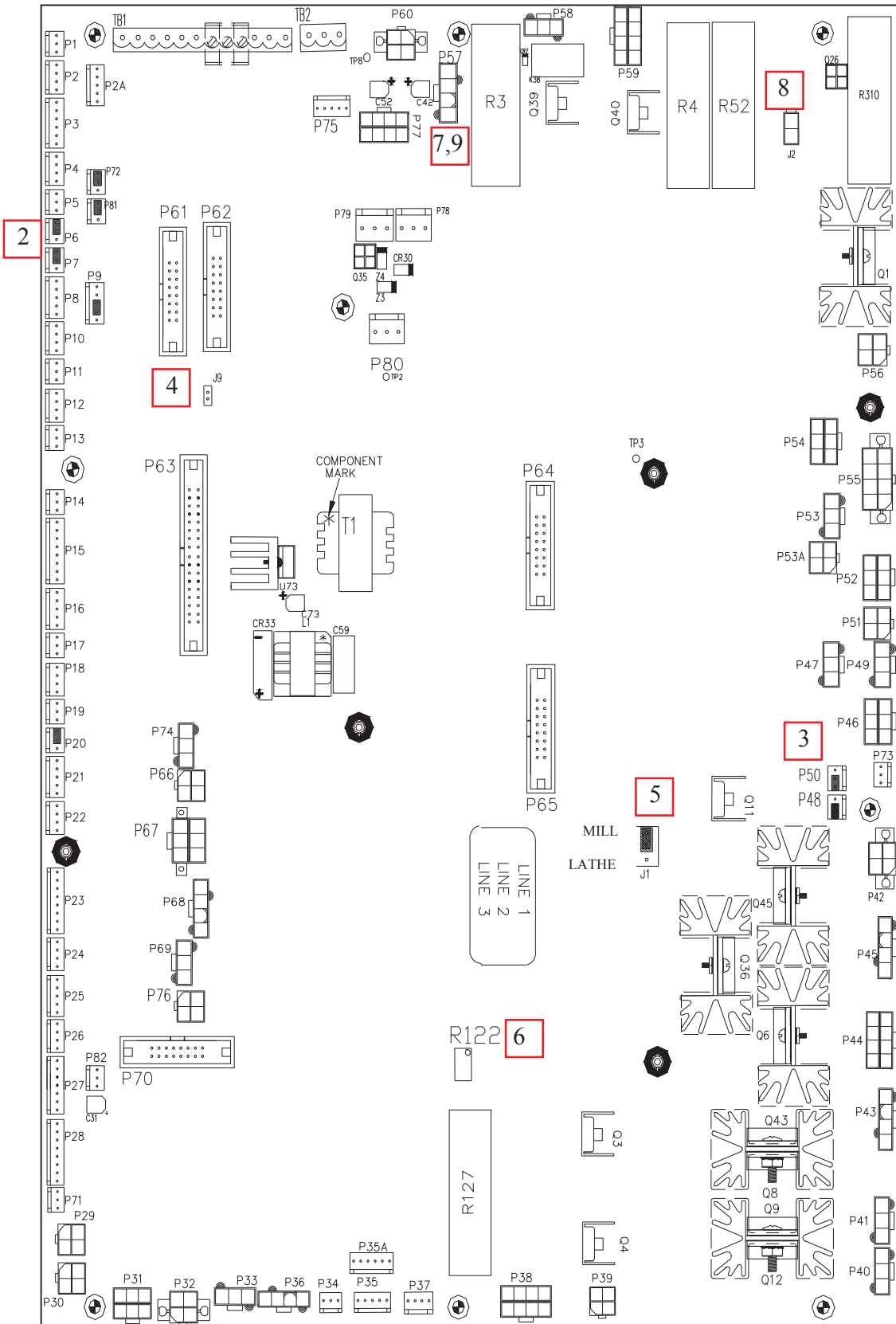
- IO-U is completely interchangeable with IO-S/IO-T. When replacing an IO-S/IO-T with an IO-U, follow the installation procedures below.
- IO-U is stuffed as three parts. 32-3083U is for the Haas SMTC. 32-3082U is a partially stuffed board for minimill, minilathe, and tool room mill. 32-3080U is for all other controls.

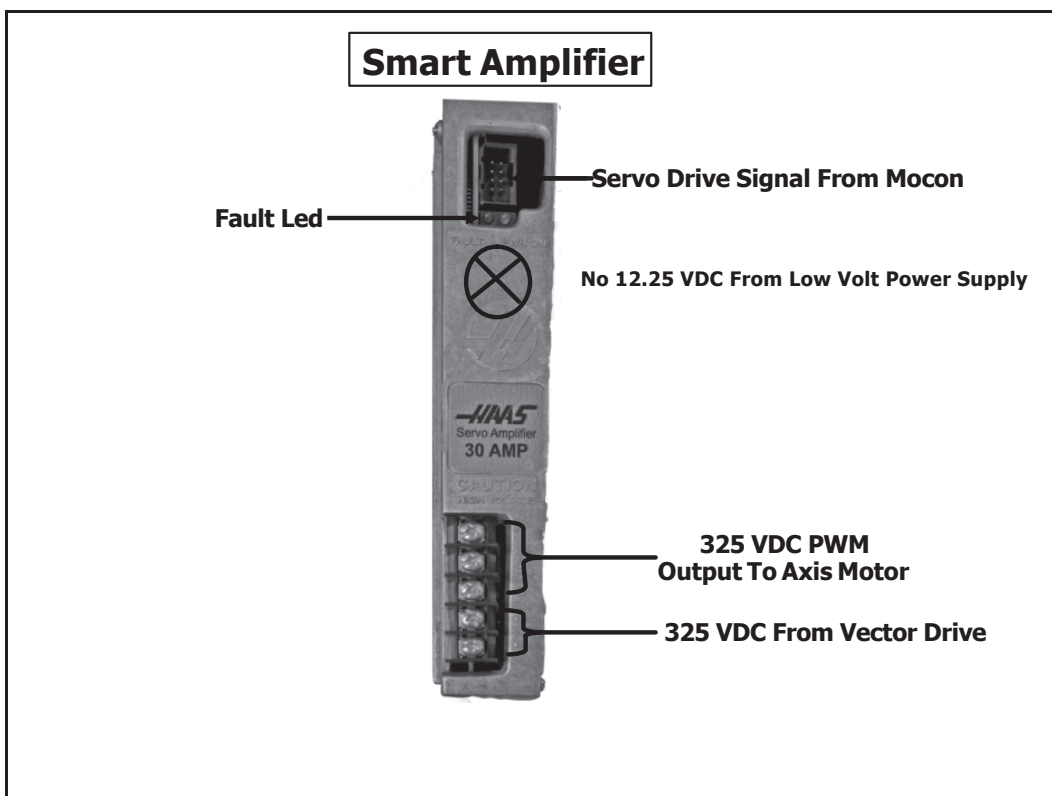
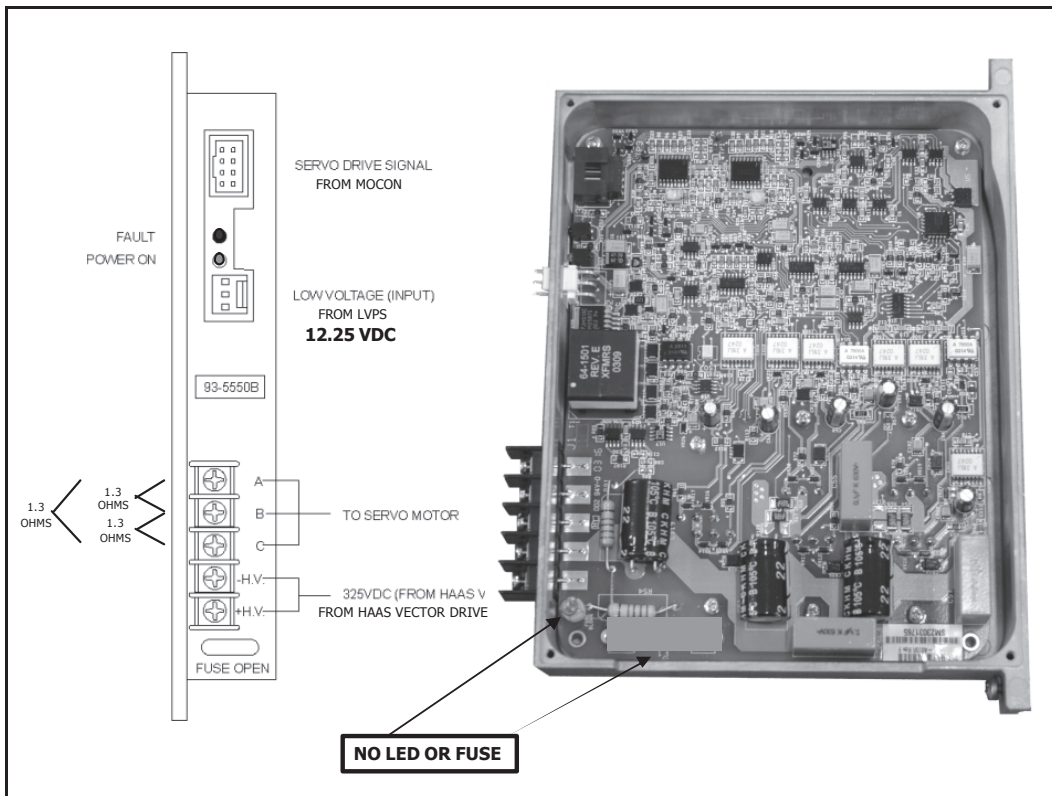
INSTALLATION PROCEDURES*Power Off:*

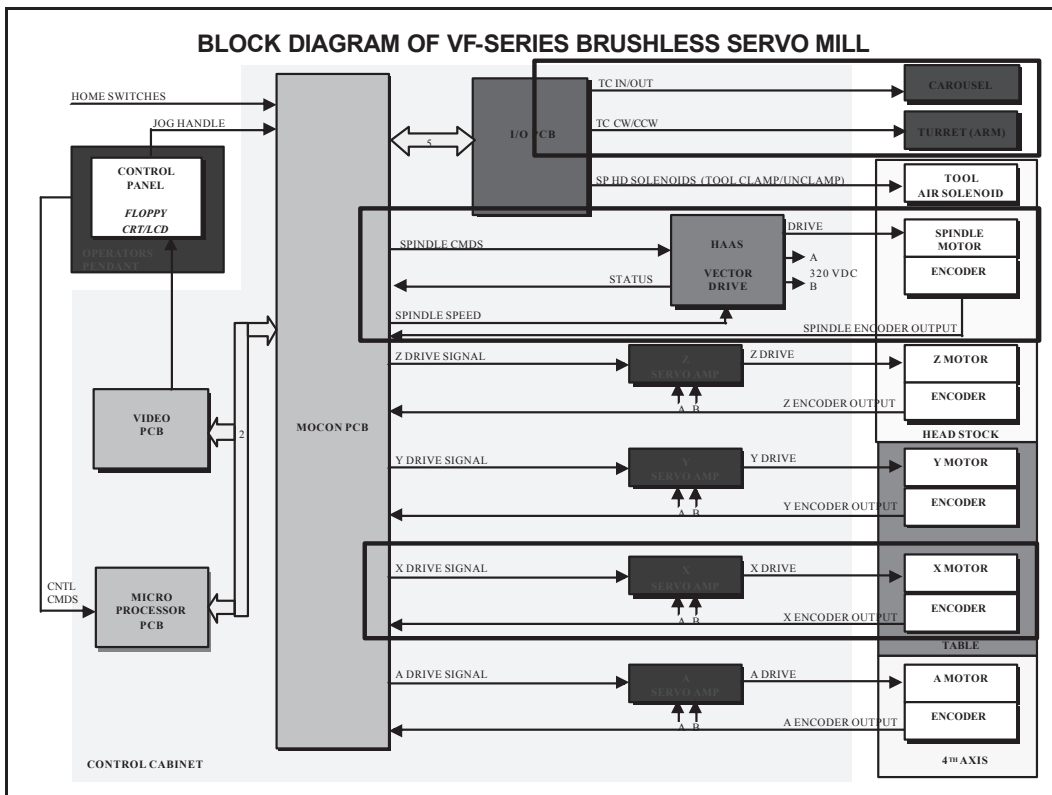
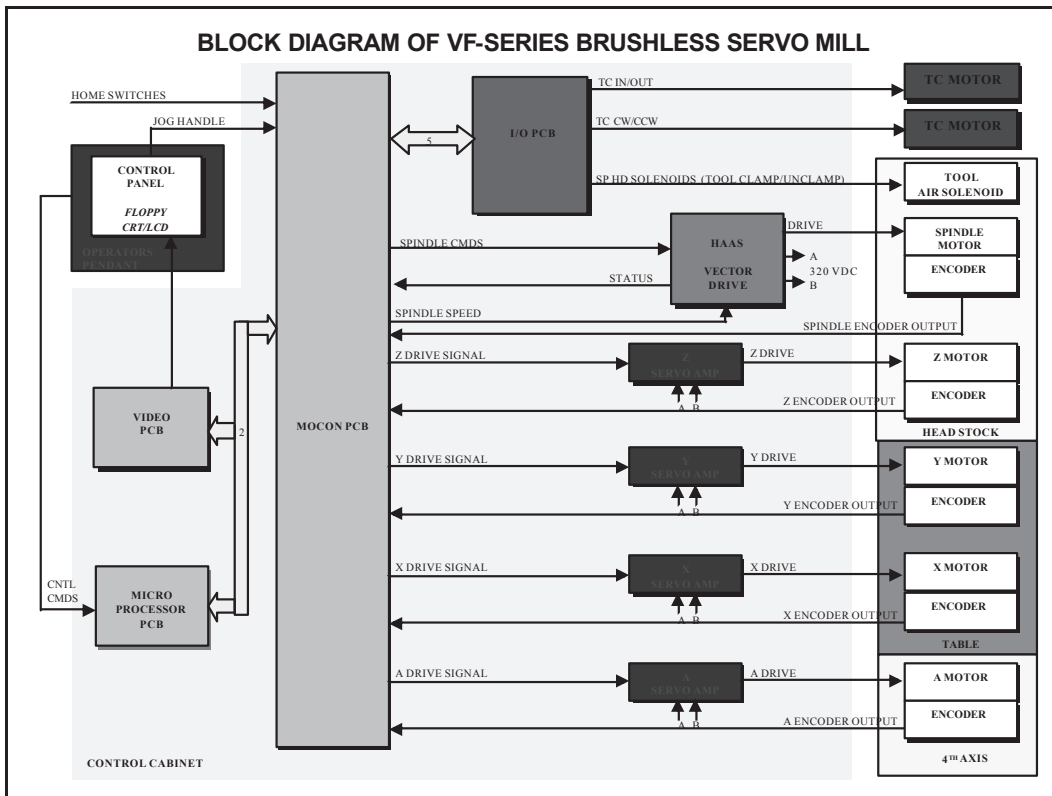
1. Review all safety text printed in the PCB silkscreen.
2. Jumper any unused E-Stop input connectors (P6 or P7). Jumper second door switch input (P9) if unused. Jumper second remote unclamped input (P20) if unused. See attached drawing for jumper placement.
3. Verify that connector's P48 and P50 are jumpered, if no cable plugs are inserted.
4. Verify that no jumper is installed at J9. This header is used for testing only.
5. Set jumper (J1) to Mill position when replacing an I/O-S or I/O-T board with an I/O-U board for both Mill's and Lathes. When replacing an I/O-U board with another I/O-U board set Jumper (J1) in the same position as the board that is being replaced.
6. Use digital ohmmeter between TP6 and TP7 to adjust chipc over current R122 to $3K\Omega$ +/- 100Ω for single-phase motors. Adjust to $4.5K\Omega$ +/- 100Ω for 1-phase, belt style, lathe chip conveyor. The machine does not need to be turned off for this adjustment only the CB4 (chip conveyor) needs to be turned off.
7. For all SL and most VF, install tc jumper cable (33-0809, supplied) at P57. Remove only if there is a cable that will plug in here instead. If this cable is too short, a longer one is in the service kit.
8. The Jumper J2 is stuffed only for service. When replacing an IO-T/S, install jumper at J2. When replacing an I/O-U, check to see if there is a jumper at J2. The new board MUST match the old.
9. When replacing with a 34-3083U make sure to use the SMTC brake resistor cable (Haas p/n 33-0815B) at P57.

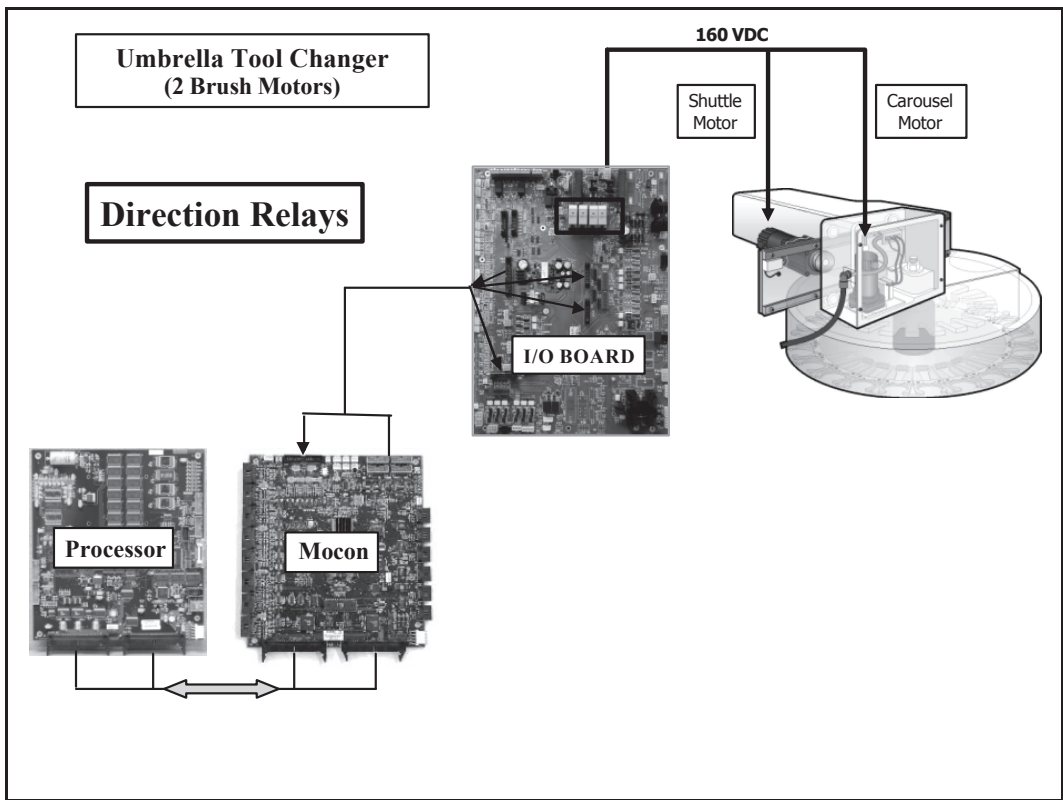
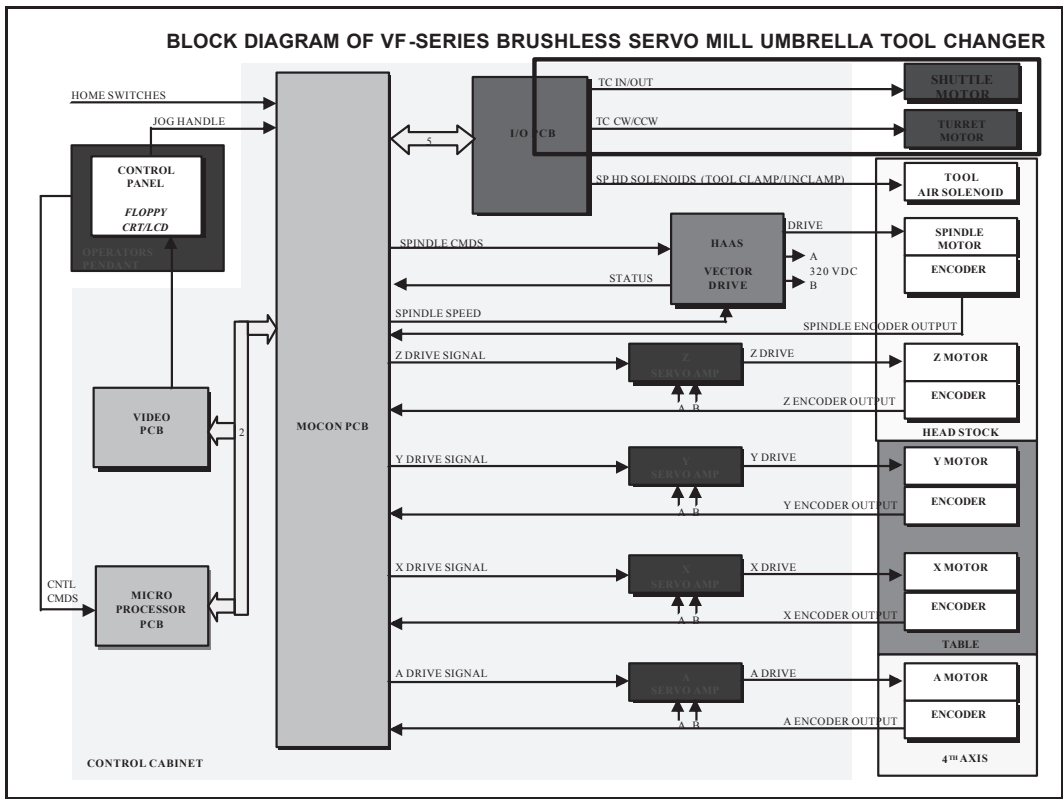
Power On:

10. Verify that parameter 209, “MCD RLY BRD”, is set to a “1”. The “Relay Bank Select” parameter 352 should be set to a 1, 2 or 3 depending on whether additional M-code relay boards are present.
11. Verify that parameter 57, “PH LOSS DET”, is set to a “0”.
12. Operate chip conveyor. If the motor will not run forward continuously, it is acceptable to decrease the over current (R122) by up to $1K\Omega$. If it still faults, replace the IOPCB and/or chipc motor. Jam the motor (using a piece of wood or by jamming the fan on the back of the motor if accessible) and verify that the motor stops and pauses before reversing (note that the belt style may not reverse, but will still pause). If it will not pause, increase the adjustment by up to $1K$.
13. Operate spindle, tool changer, coolant, tsc, spigot, e-stop, beacon, door, and all optional equipment (pallet changer, barfeeder, etc.). Verify correct operation.

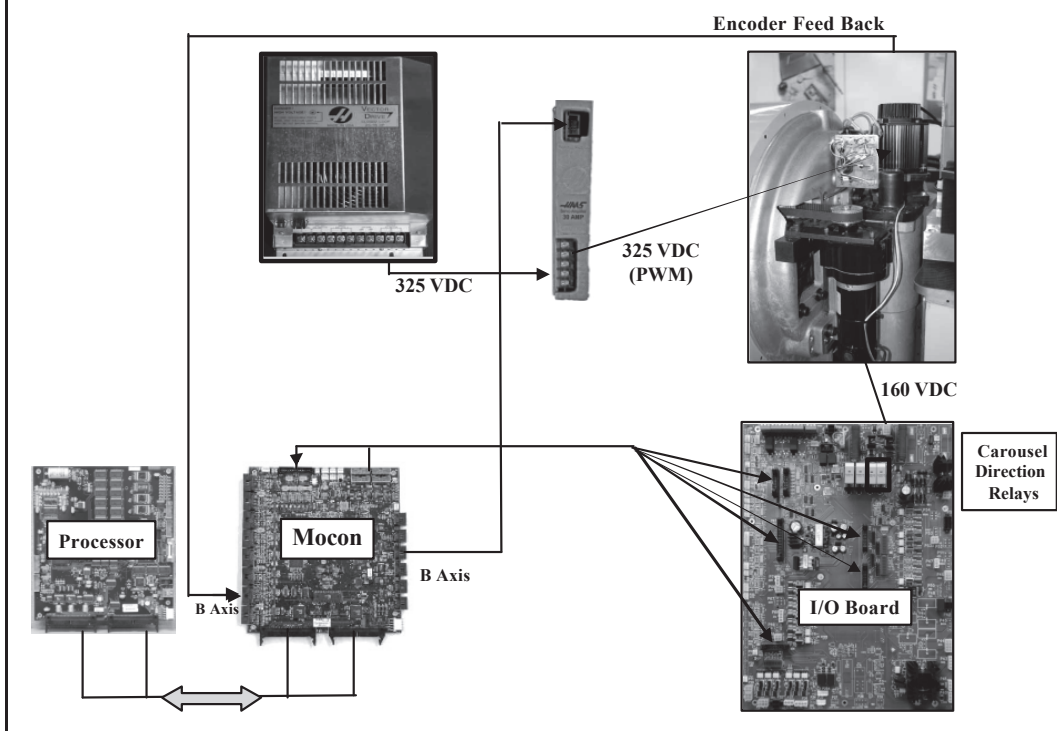




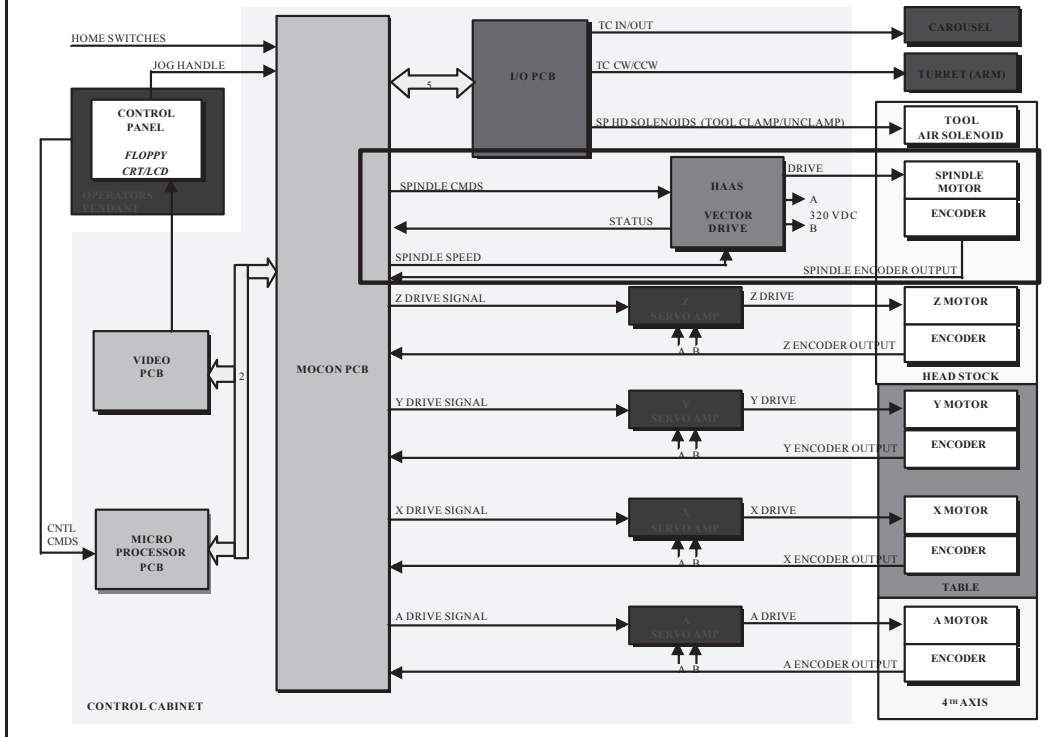


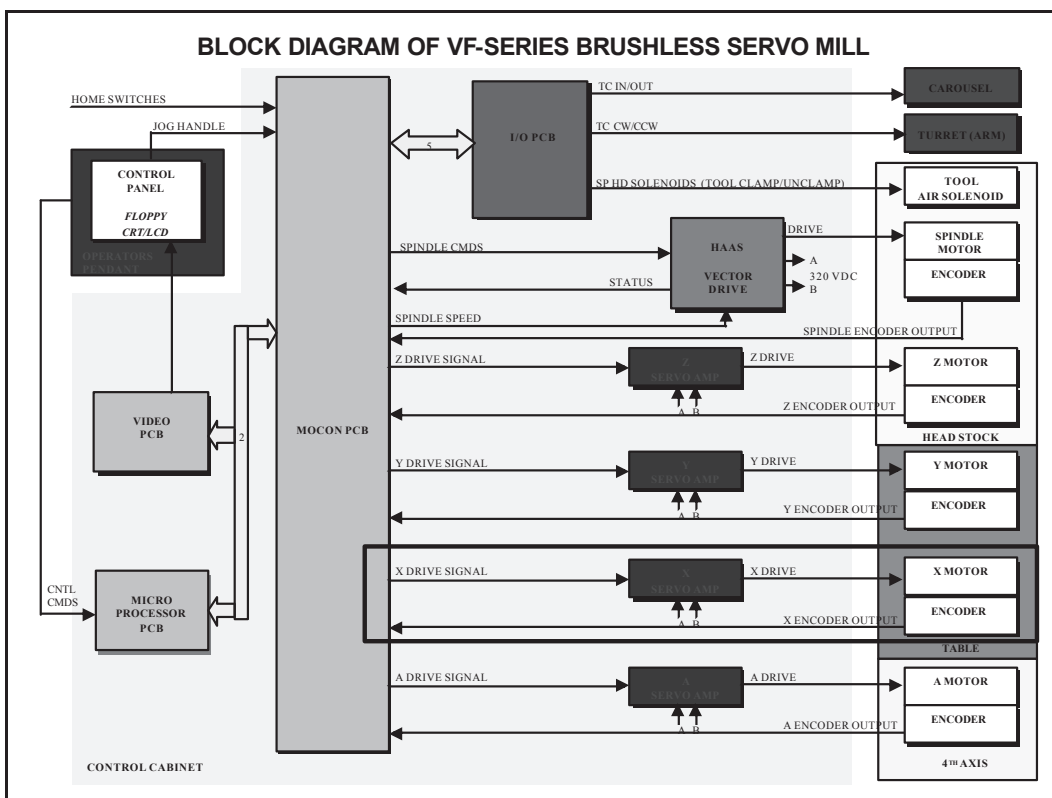
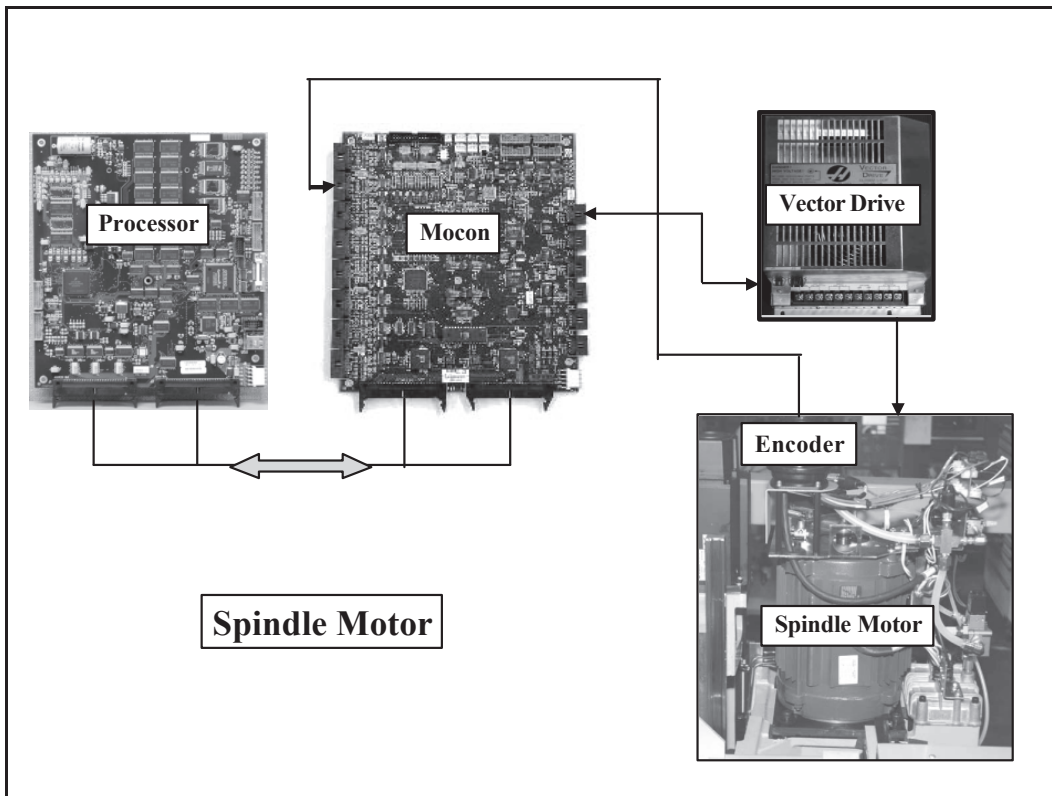


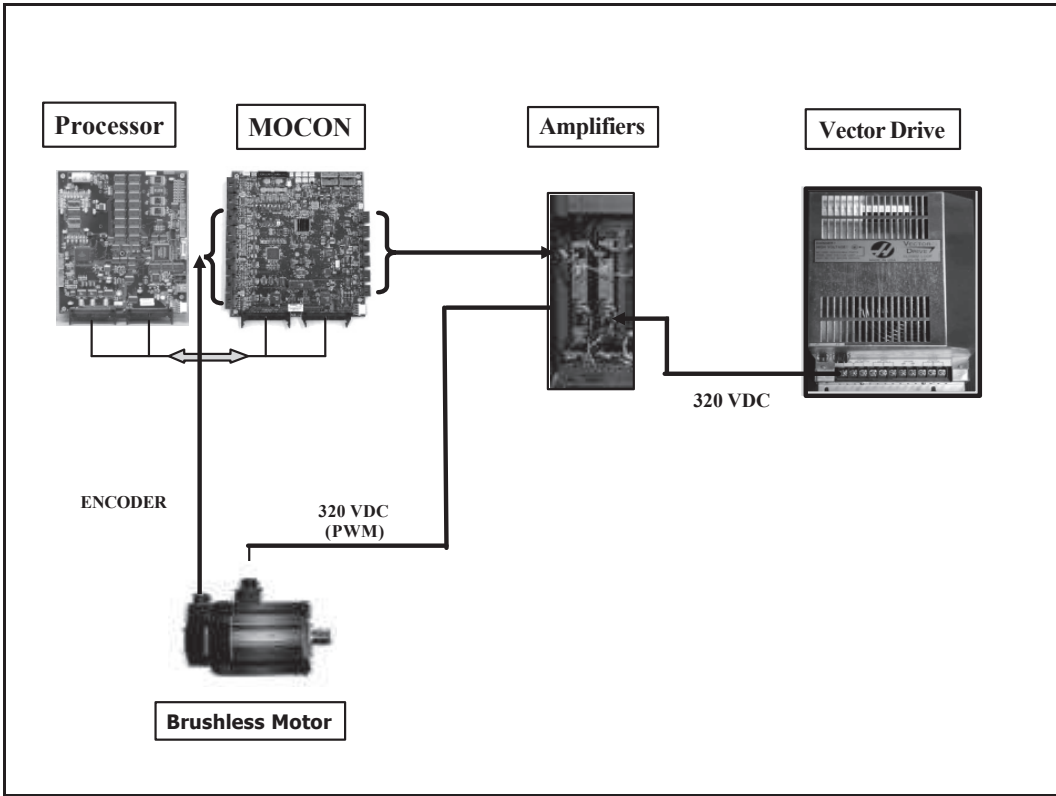
Super Speed Side Mount TC (1 Brush & 1 Brushless Motor)



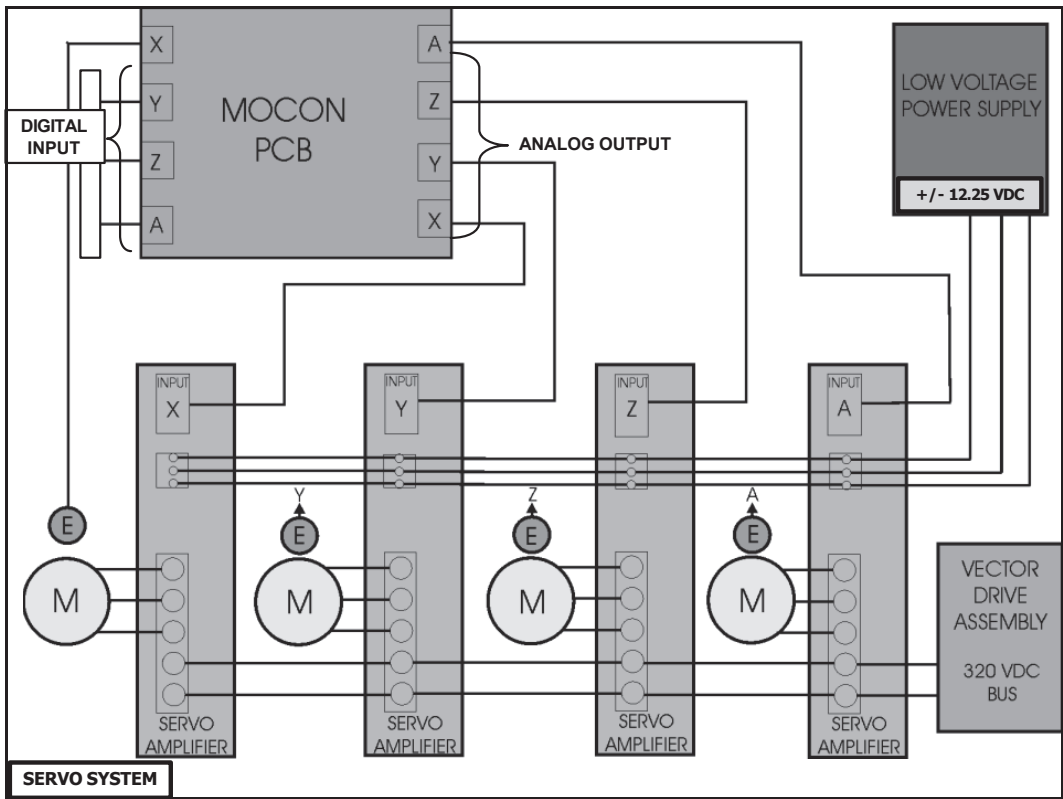
BLOCK DIAGRAM OF VF-SERIES BRUSHLESS SERVO MILL



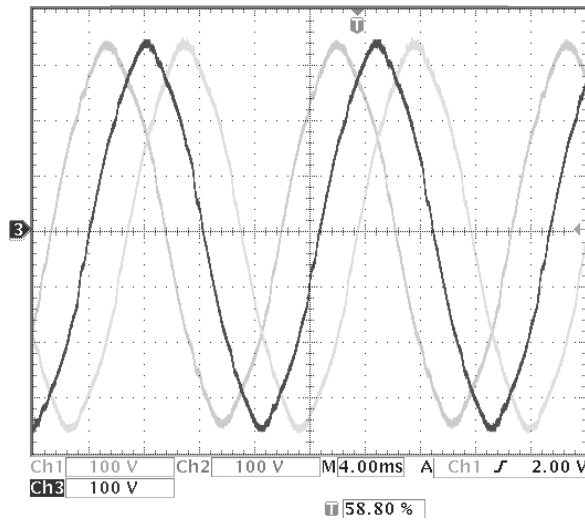




Servo System

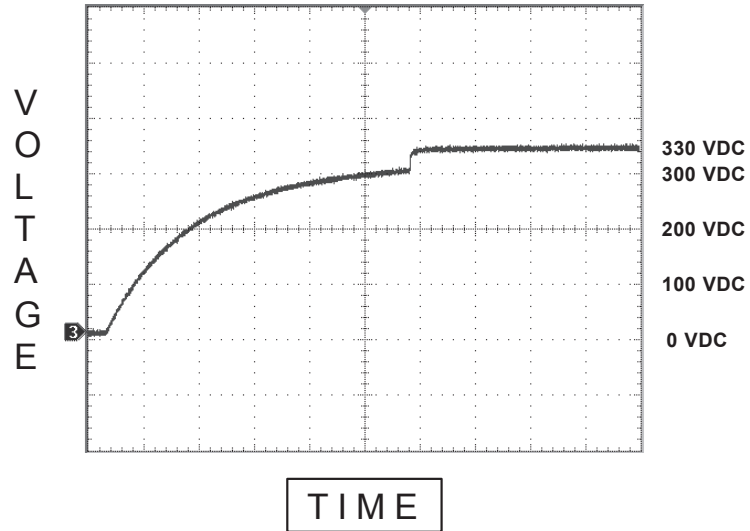


3 PHASE 230 VAC INCOMMING LINE VOLTAGE

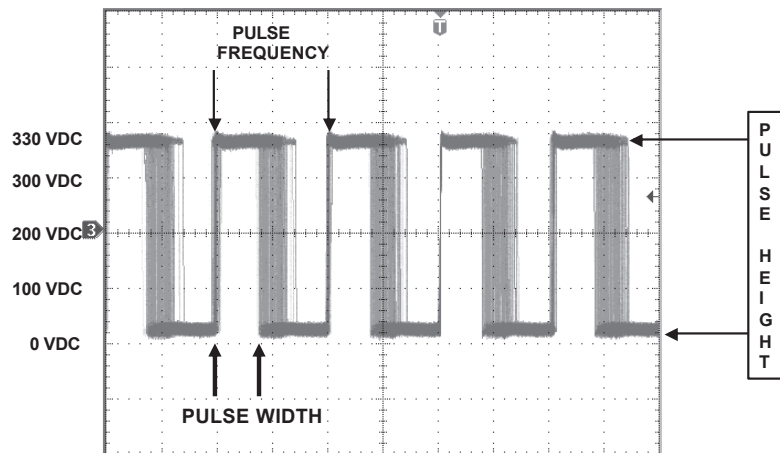


24 Jan 2006
17:18:51

320 VDC BUSS VOLTAGE TO SERVO AMPS



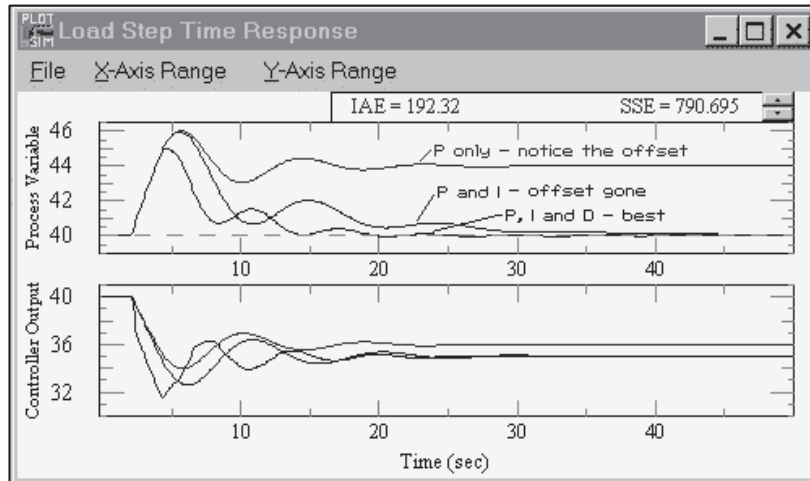
PULSED WIDTH MODULATION (PULSED DC TO SERVO/SPINDLE MOTOR) FROM AMPLIFIER/VECTOR DRIVE



PID - LOOP

P GAIN - I GAIN - D GAIN

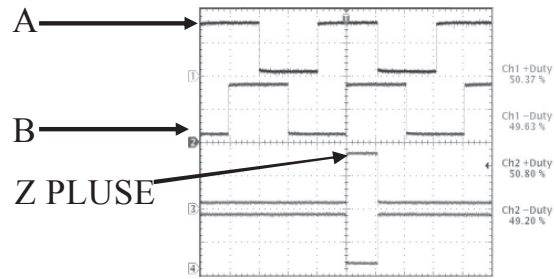
PROPORTIONAL-INTERGAL-DERIVATE



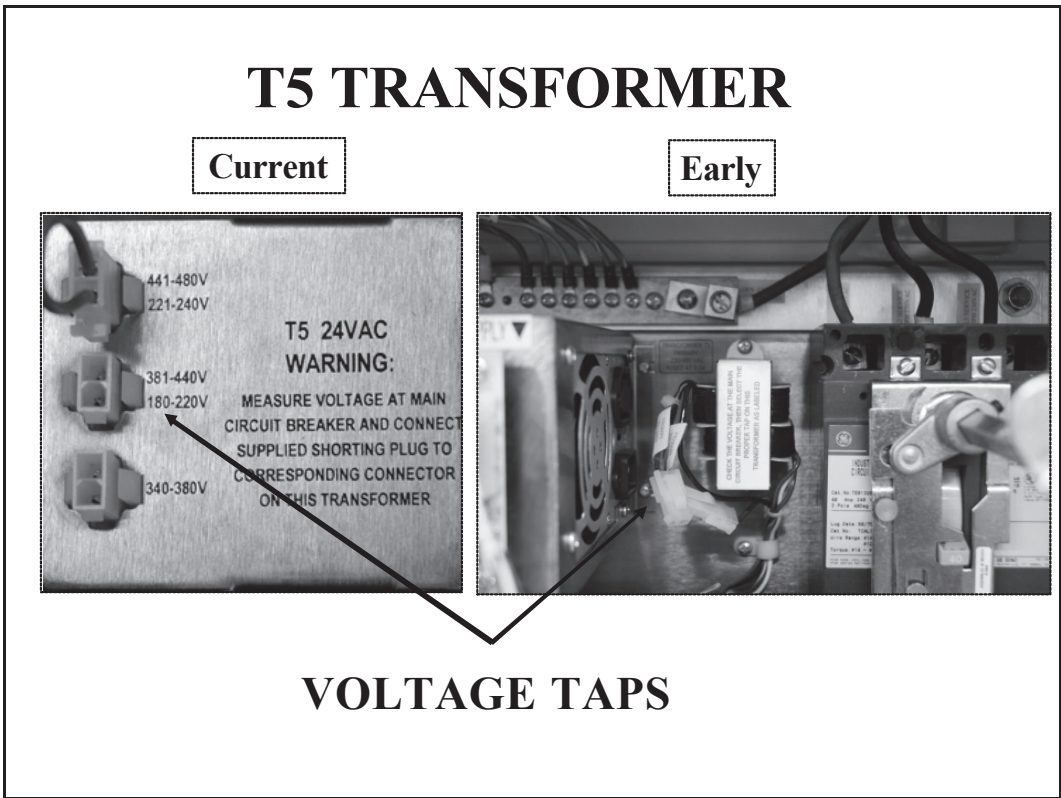
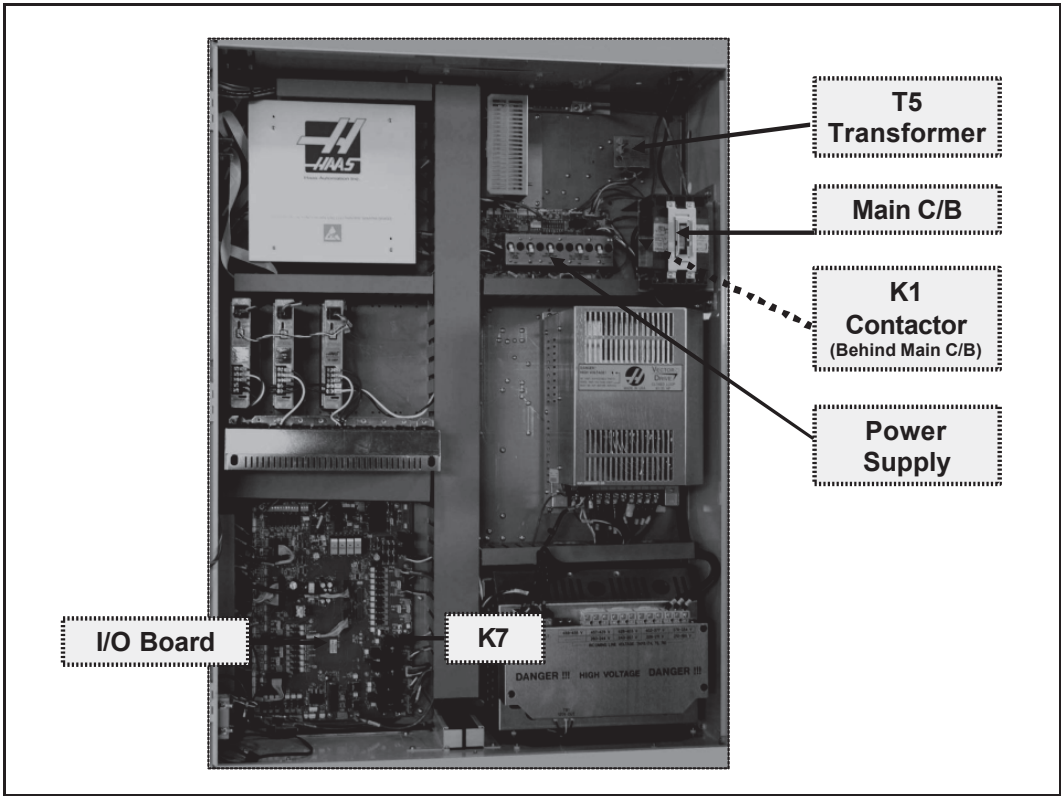
PARAMETERS (ZERO RET)		081002 N00000000
X	PARAM A	
X	P GAIN	2: 48
X	D GAIN	3: 4000
X	I GAIN	4: 64
X	RATIO (STEPS/UNIT)	5: 138718
X	MAX TRAVEL (STEPS)	6: 1172167
X	ACCELERATION	7: 6000000
X	MAX SPEED	8: 1638400
X	MAX ERROR	9: 16384
X	FUSE LEVEL	10: 3000000
X	BACK EMF	11: 550
X	STEPS/REVOLUTION	12: 32768
X	BACKLASH	13: 12
X	DEAD ZONE	14: 8
X	IN POSITION LIMIT	101: 16000
X	MAX CURRENT	105: 4095
X	DxD GAIN	109: 1000

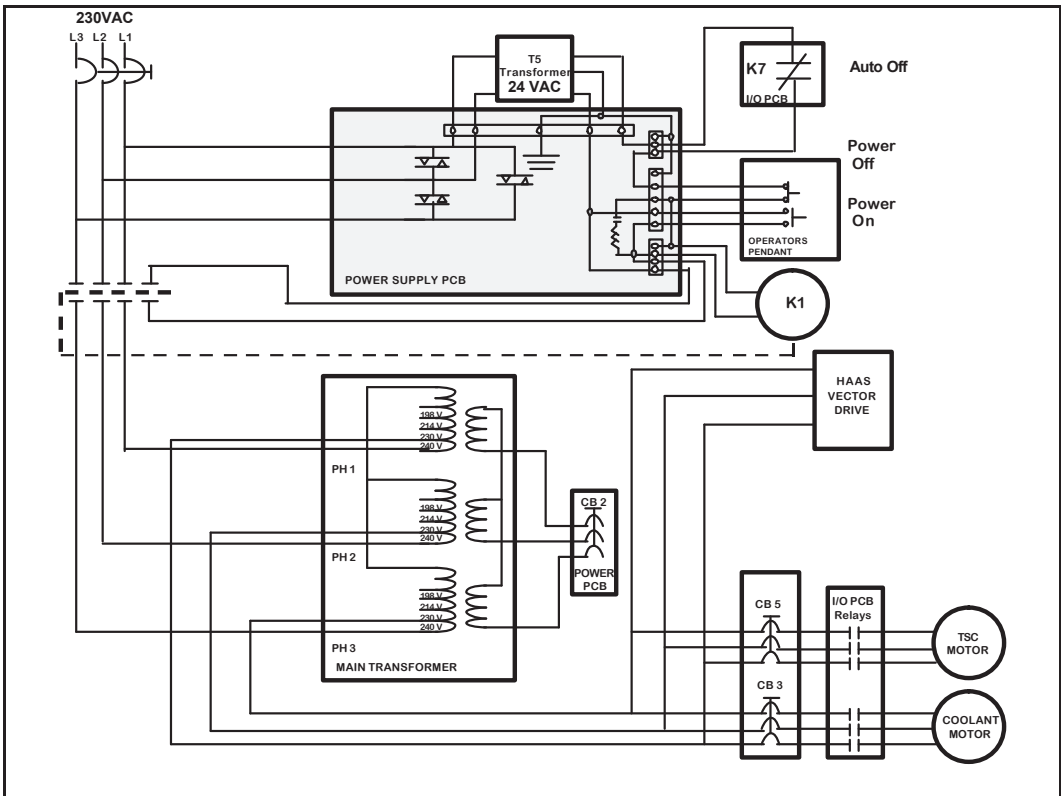
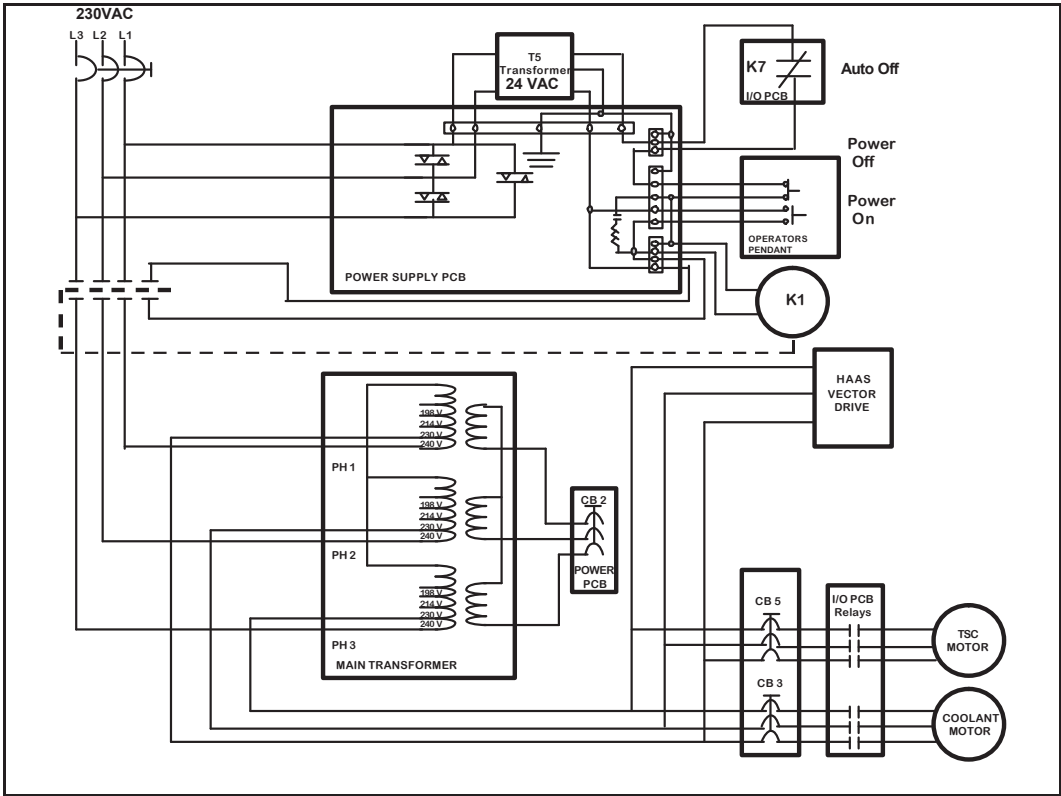
ENCODER SIGNAL (FEED BACK TO MOCON)

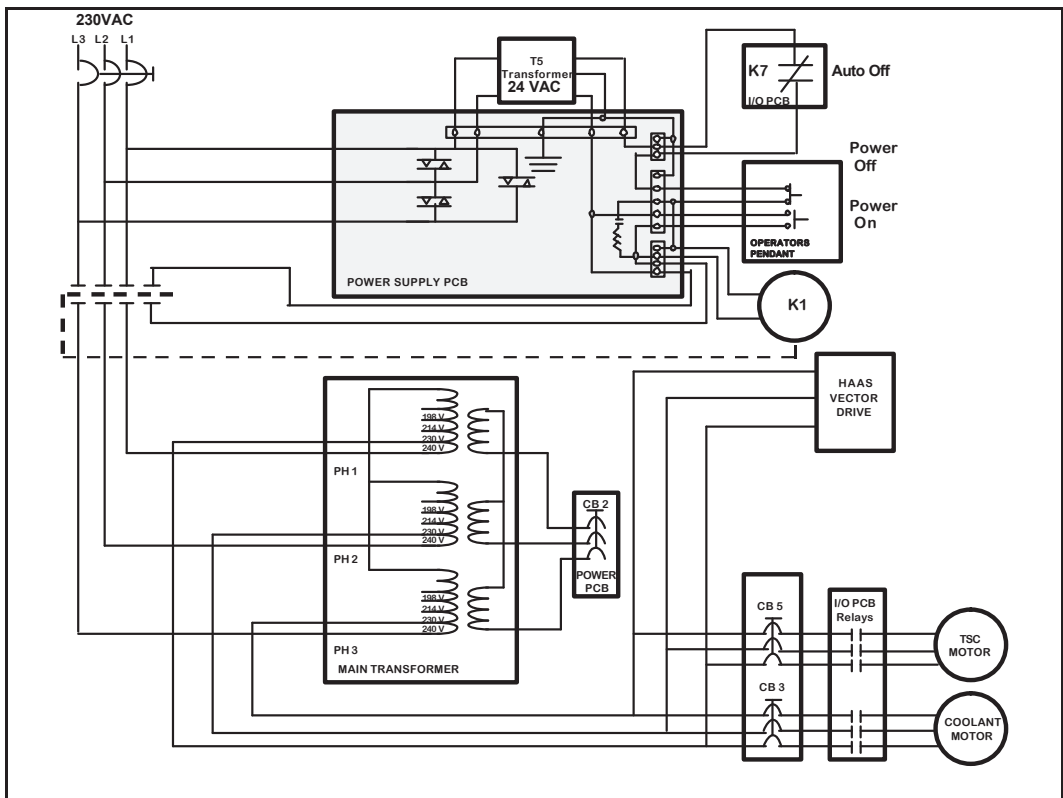
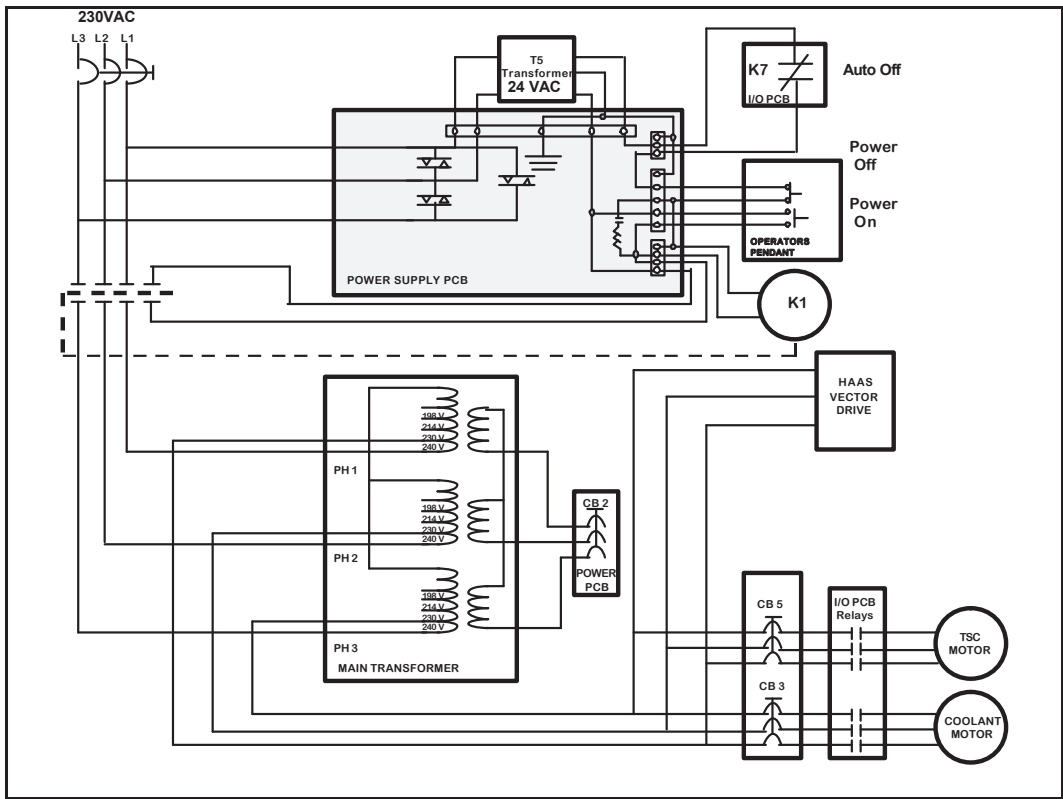
Scope CH1-4 correspond to encoder signals A, B, Z & Z not respectively. The encoder signal phasing, voltage levels, and duty cycle, shown below, all meet Haas requirements. In addition these encoders meet or exceed the Haas requirements as provided in the 60-1815 specification.

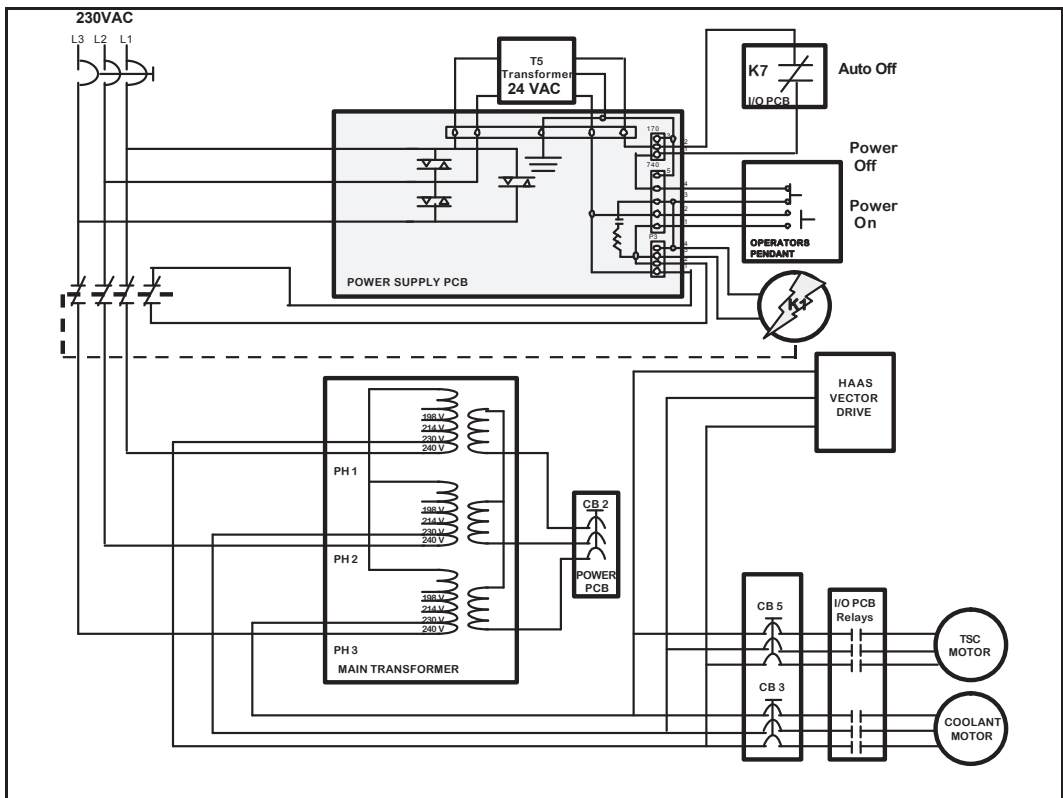
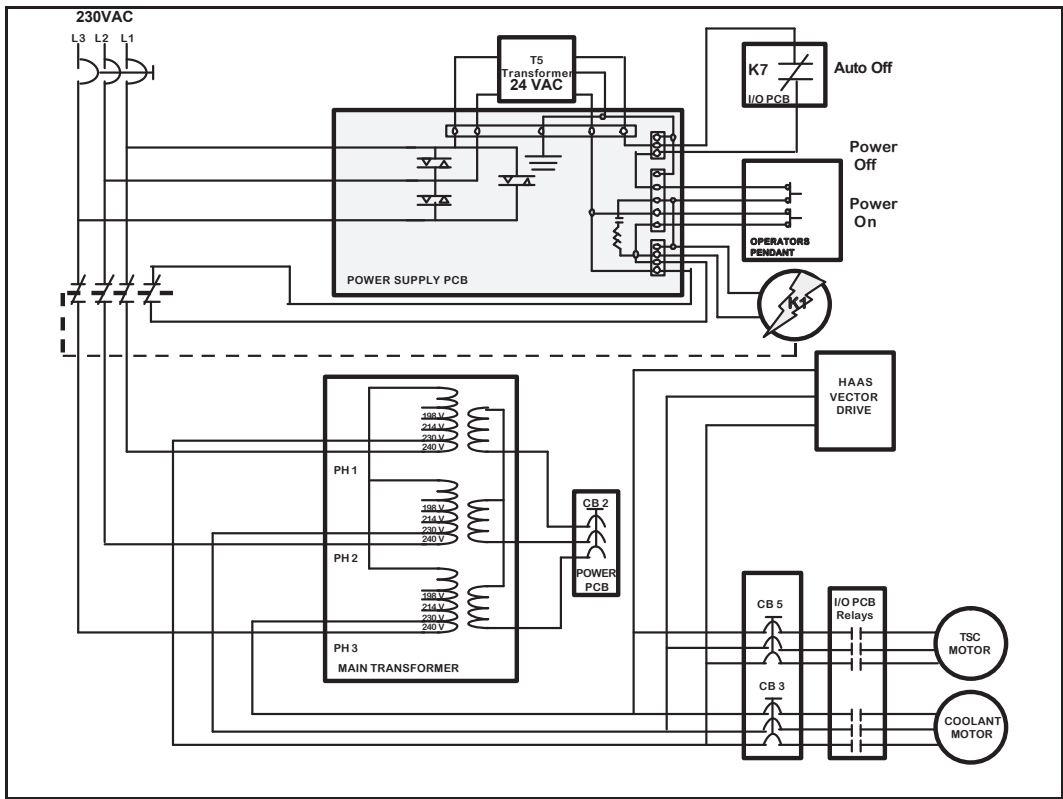


Power On Circuit



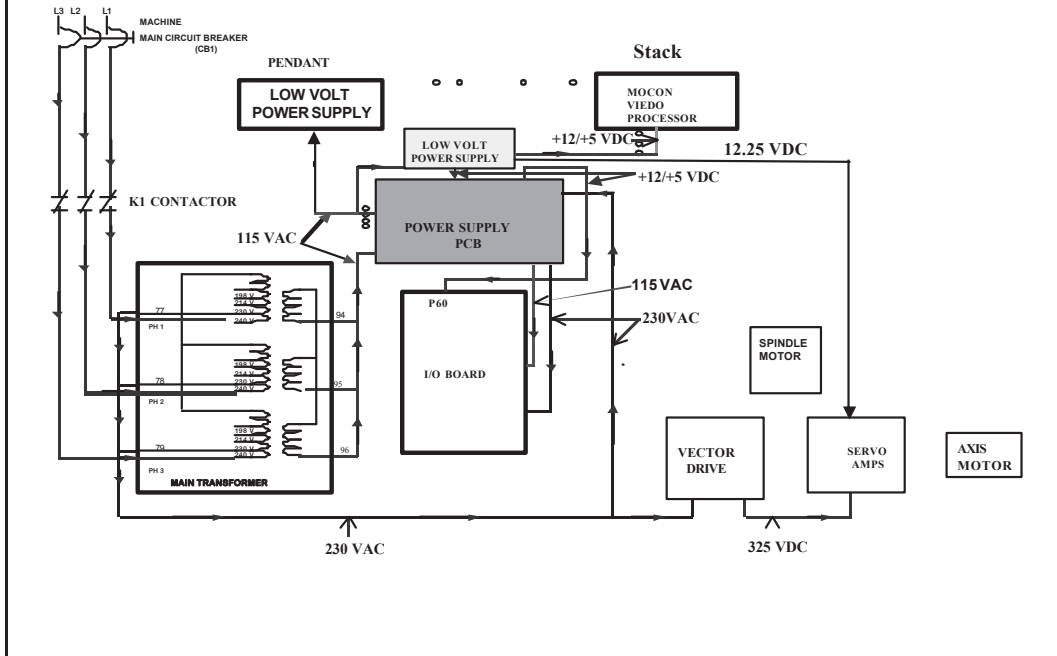






POWER ON SERVOS/SPINDLE NOT ENERGIZED

WHERE THE POWER GOES AFTER THE POWER ON BUTTON IS RELEASED



Prepared by Haas Automation
Service Training Department
Oxnard, CA 93030